

TotalControl – an overview

Advanced integrated control of WPPs



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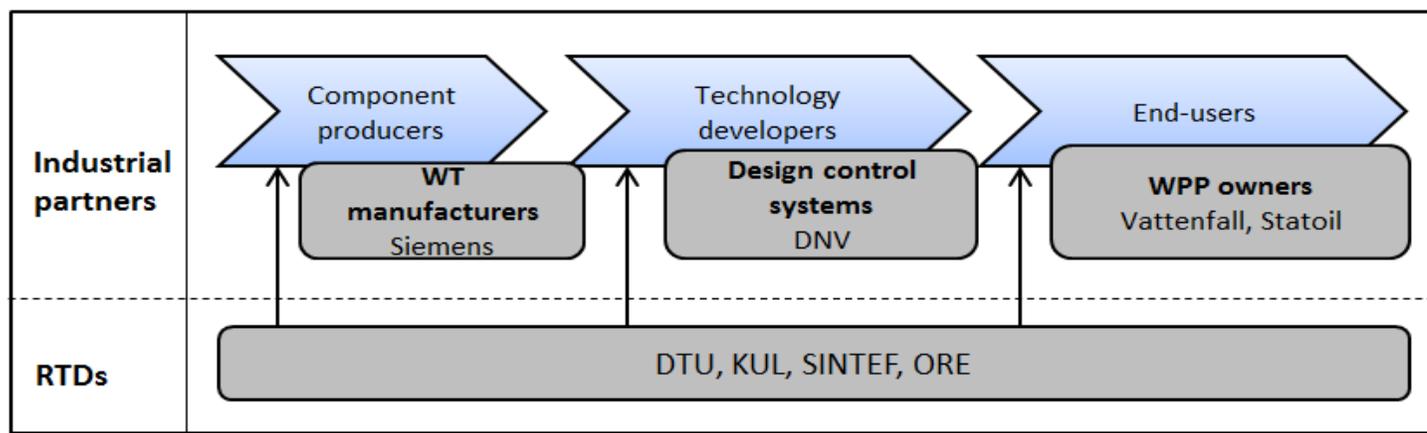
Outline

- Consortium
- Overall objectives and approach
- How? – project structure
 - WP₁ + selected high lights
 - WP₂ + selected high lights
 - WP₃ + selected high lights
 - WP₄ + selected high lights
 - Wp₅ - dissemination



Consortium

Participant no	Participant Organisation Name	Country
1 (Coord.)	Danmarks Tekniske Universitet (DTU)	DK
2	Katholieke Universiteit Leuven (KUL)	BE
3	SINTEF Energi (SINTEF)	NO
4	Garrad Hassan & Partners Ltd (DNV)	UK
5	Vattenfall (VF)	SE
6	ORE Catapult (ORE)	UK
7	Siemens (SWP)	DK
8	Statoil (Statoil)	NO



Overall objectives

- To develop *integrated* WPP/WT control strategies conditioned on grid demands ... that *maximize* the life-cycle *profitability* of a WPP
 - Maximizing *power* production balanced against turbine *loading* (i.e. fatigue load degradation of WTs and O&M costs) and electricity price
 - Enhancing WPP capability to provide *ancillary services*
- To validate derived models: All WPs include *experimental validation* ... WP₁, WP₂, and WP₃ include full-scale experiments; WP₄ include lab. scale experiments



Approach

- The ambition of TotalControl is to move WPP controller design philosophy from *greedy individual* optimization of WTs operation to a *collaborative* optimization of the overall WPP performance



WP's

WP1: WPP design and control models

Goal

- Development of appropriate control models for other WPs
- Set up of virtual testing environment that can be used in other WPs

To that end:

- Measurement campaign in Lillgrund
- Use of high-fidelity numerical simulation models (SP-Wind, SOWFA, Ellipsys)

WP2: quasi-static open-loop WPP control

Goal

Wind-farm control with **control time steps of 10-20 min**

To:

- Improve power extraction by yawing
- Reduce loads (steered by lifetime and O&M costs/timing) by yawing, or induction control
- Decide on WPP downrating in response to market, tertiary ancillary services
- ...

VERIFICATION/VALIDATION

- Experiments @ Lillgrund
- Use virtual simulation environment

WP3: WT control

Goal

Enhance WT control **control time step: < 1s**

To:

- Further load reduction
- Turbulence or market based derating
- Primary ancillary services (FFR, Voltage support)
- Allow other and dynamically changing set-points – widen available operational range for controllers in WP2 and WP4
- LIDAR assisted control
-

- Experiments on the Samsung 7MW turbine

WP4: feedback WPP control

Goal

Wind-farm control with **control time steps < 1 min**

To:

- Dynamic optimization
- Reduce loads (subject to turbulent gusts)
- Provide primary and/or secondary ancillary services (e.g. power signal tracking)
- Increase energy extraction (subject to turbulence)
- Deep understanding of WPP system dynamics

- Laboratory experiments
- Use virtual simulation environment (validated in WP1)

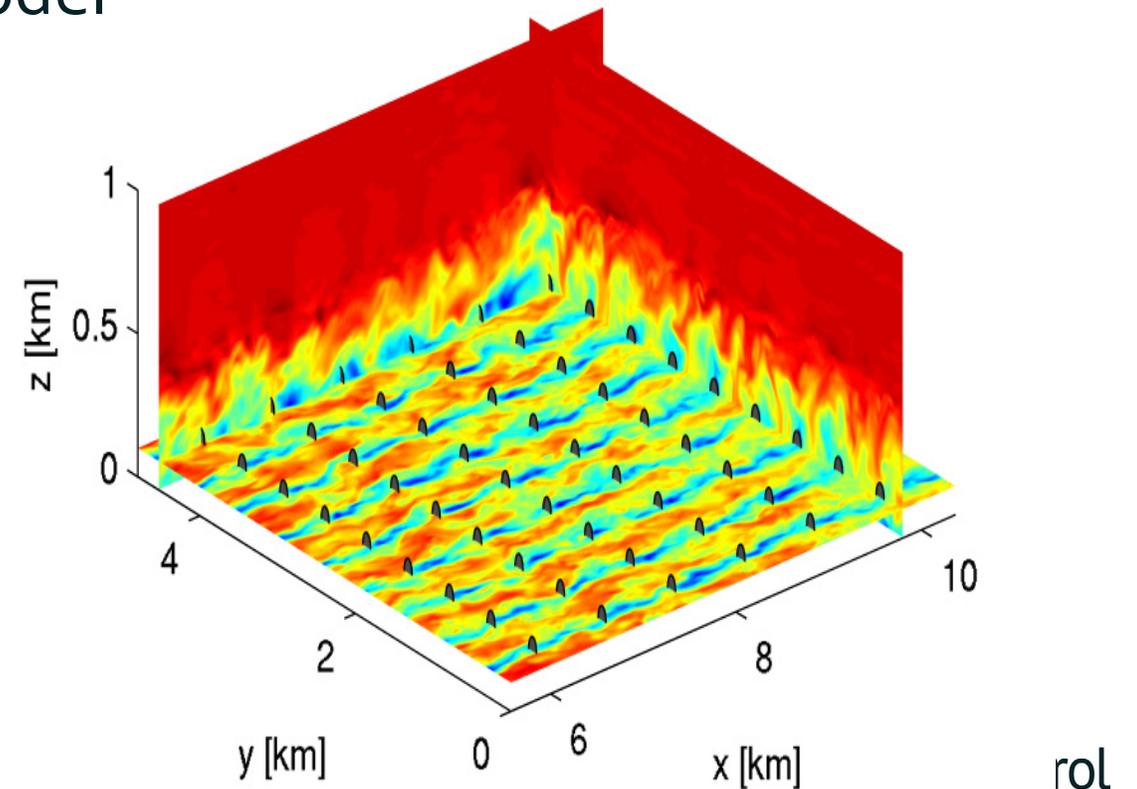
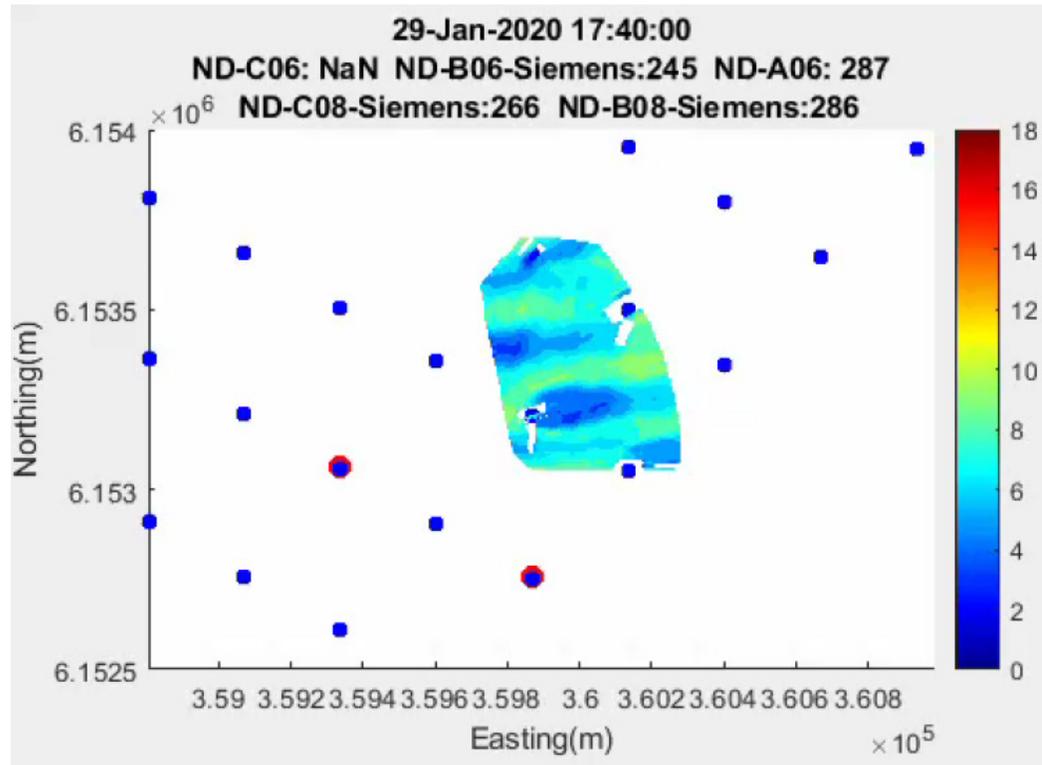
WP5: DISSEMINATION

WP6: MANAGEMENT



WP₁ - WPP simulation models (1)

- **Objectives:** *Development* and *validation* of WPP simulation models of *various fidelity* ... covering the *whole chain* from flow model over aero-elastic model to power-grid model



WP₁ - WPP simulation models (2)

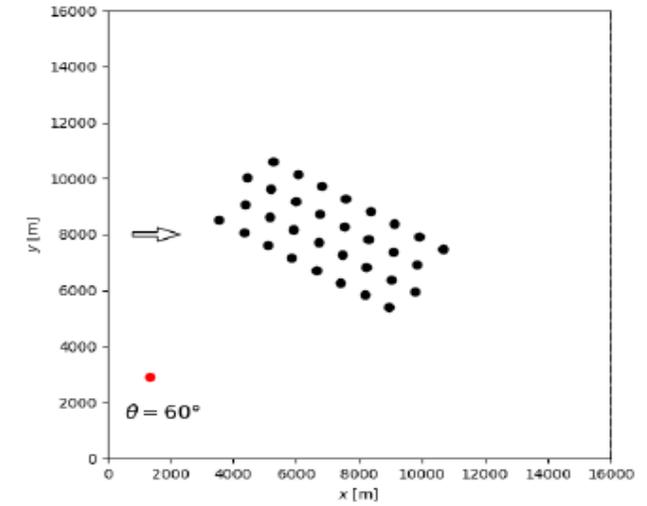
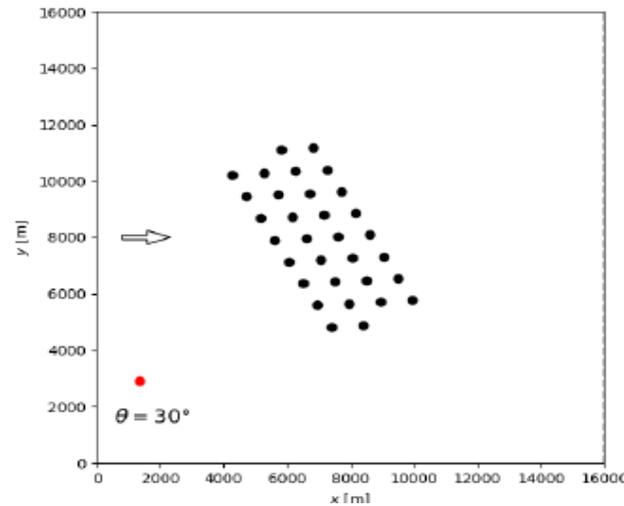
- **Modeling – High fidelity; medium fidelity; engineering:**
 - CFD LES simulations; **dynamic**
 - DWM ... generalized to account for yawed WTs; **dynamic**
 - Linearized CFD RANS (Fuga - super fast 😄) ... generalized to account for yawed actuator disc WTs; **static**
 - Simple dynamic wind farm model (LongSim; eng. wake model embedded in dynamic flow field); **dynamic**
 - Coupling of Gaussian wake model to background ABL model; **static**



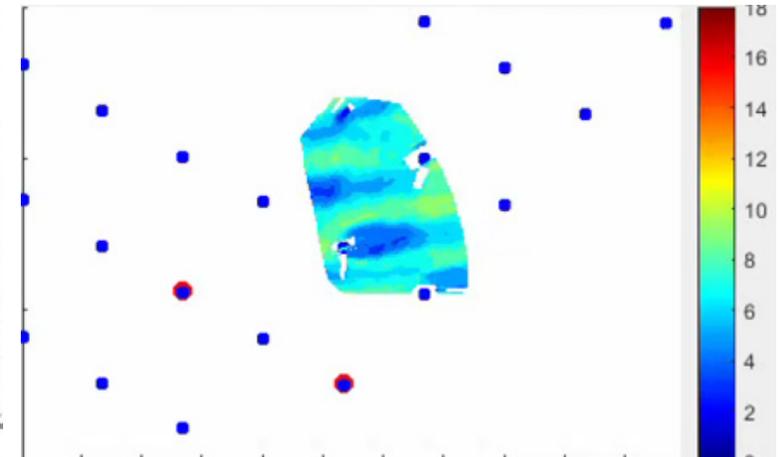
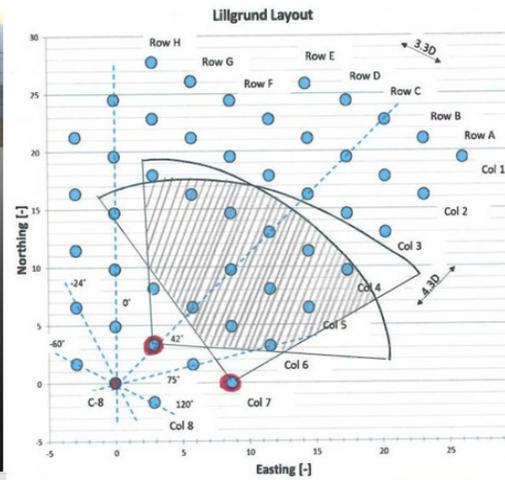
WP₁ - WPP simulation models (3)

- Show cases – demonstration, validation:

- Reference wind farm including power grid

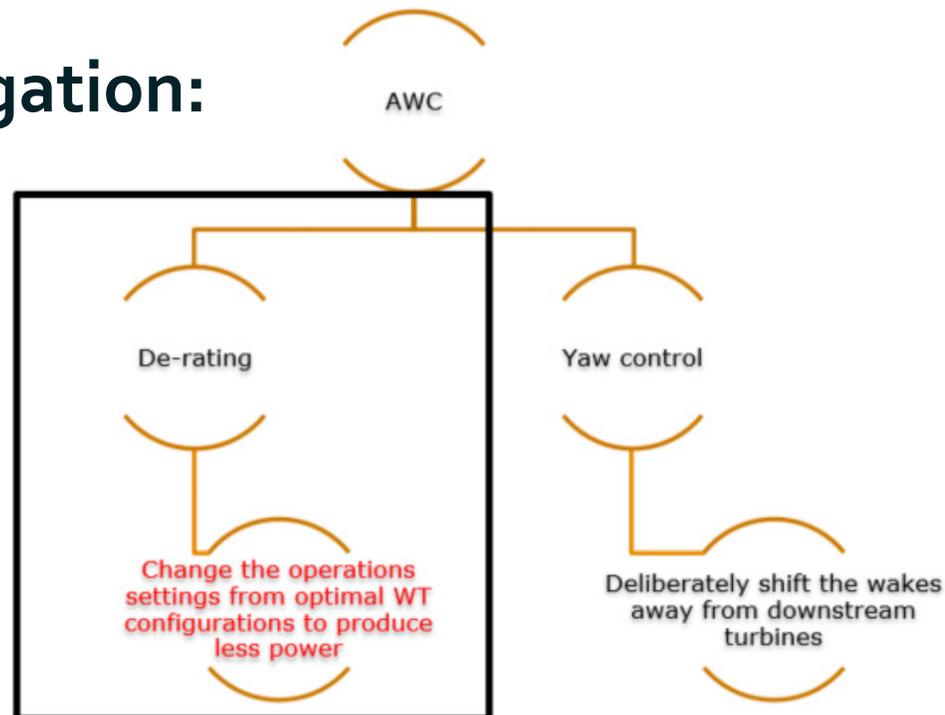


- Lillgrund



WP2 – Open loop control schemes (1)

- **Objectives:** Develop and validate *optimized WPP control schemes* ... optimal economic WPP performance (power, load and electrical aspects) is pursued over the WPP life time ... on *time scales of the order of 10 minutes*
- **Approach ... wake mitigation:**

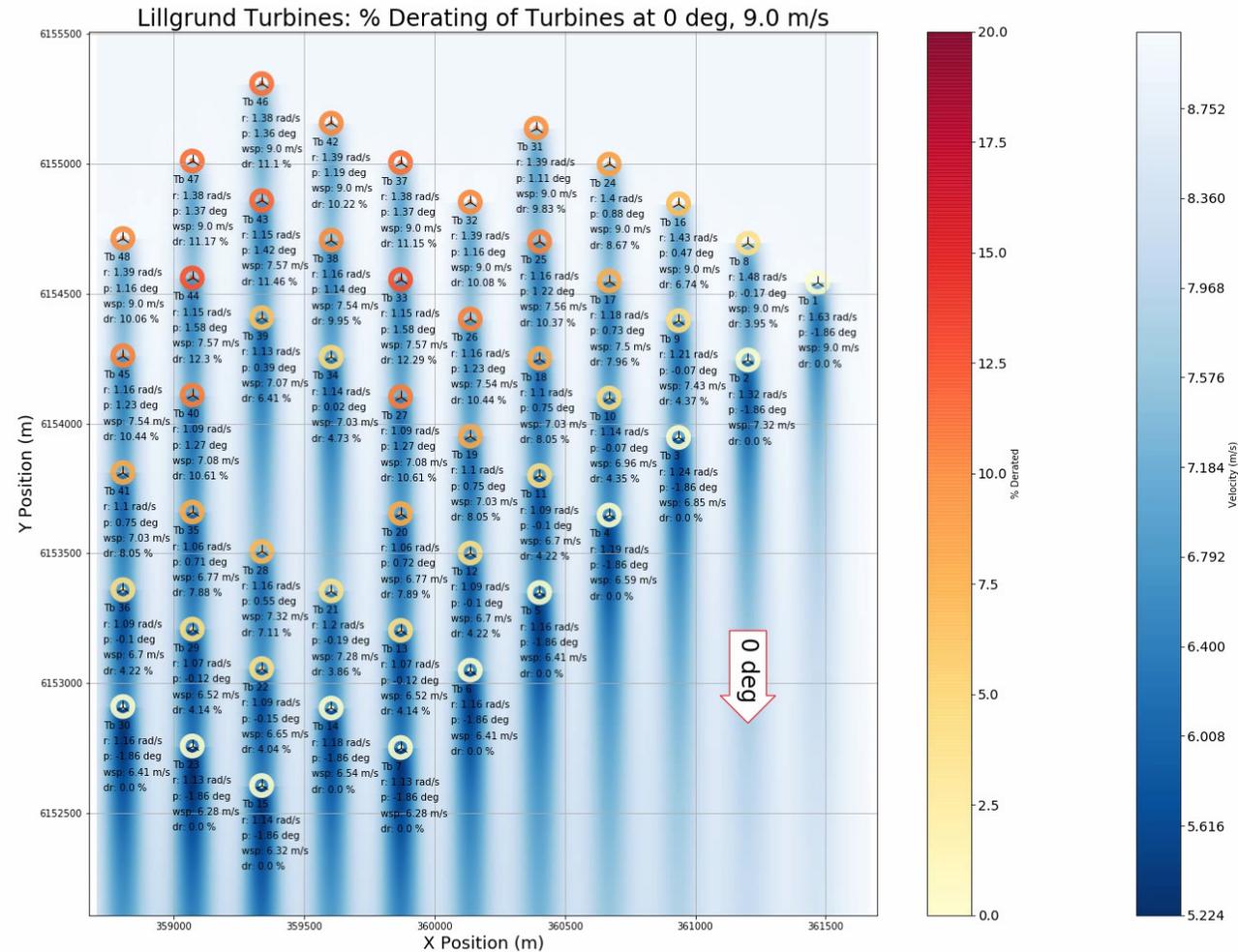


WP2 – Open loop control schemes (2)

- **Optimal WPP control schedules – static approach**
 - Objective function: WPP power production | (U, Θ)
 - De-rating using 2 design variables pr. WT ... Ω and α_p
 - WTs modeled as actuator discs in Fuga (linearized CFD code)
 - Lillgrund show case

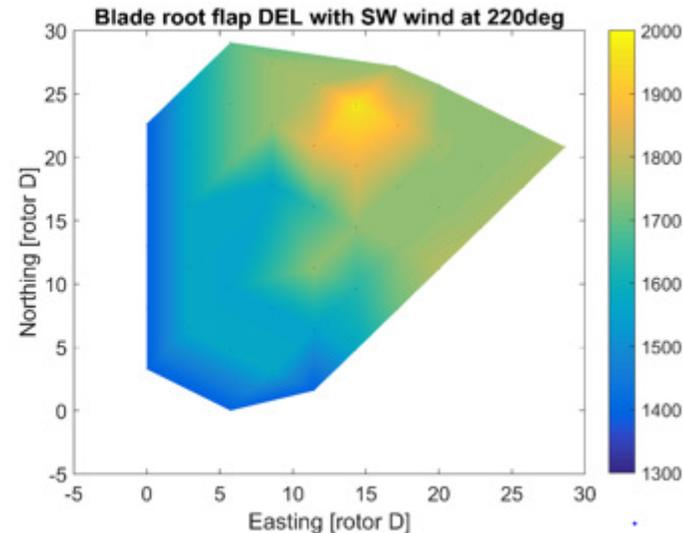
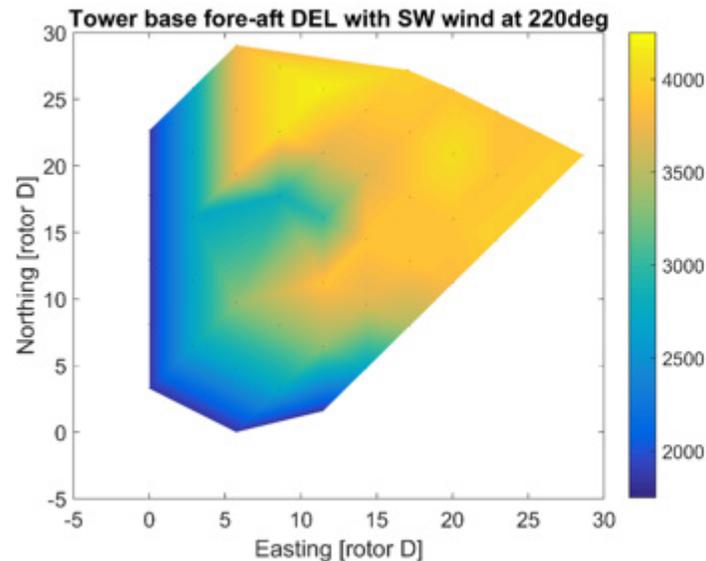


WP2 – Open loop control schemes (3)



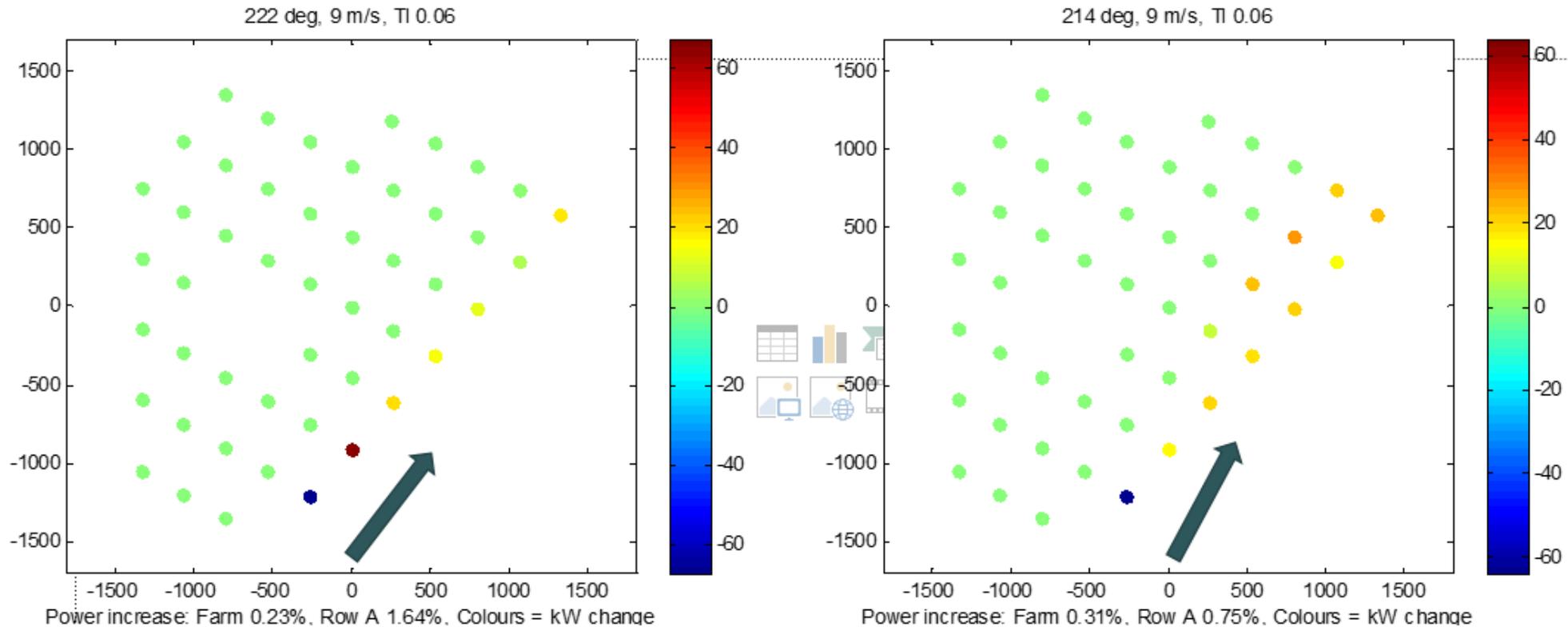
WP2 – Open loop control schemes (4)

- **Optimal WPP control schedules – dynamic approach**
 - Keyword: surrogate models ... due to CPU issues
 - Lillgrund show case



WP2 – Open loop control schemes (5)

- Full scale de-rating validation case – power capture; Lillgrund



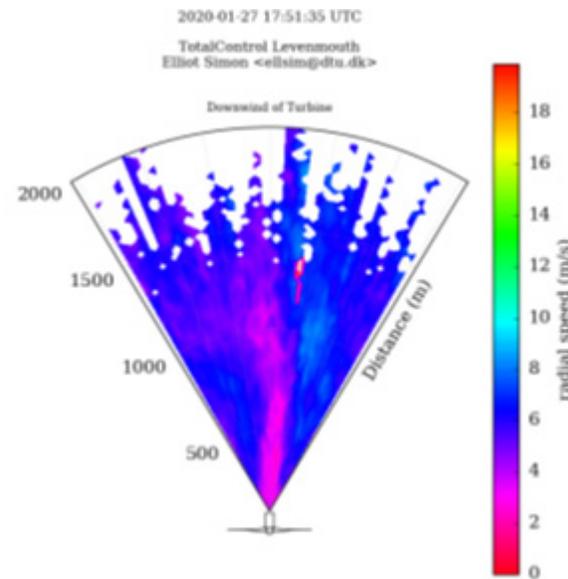
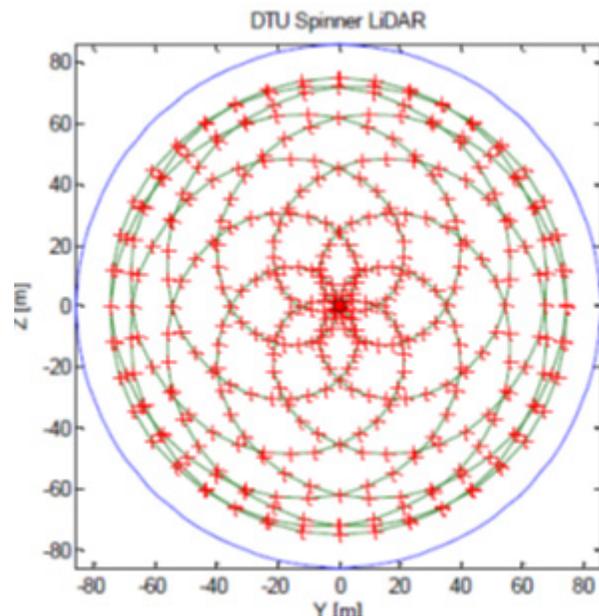
WP₃ - Enhanced WT control schemes (1)

- **Objectives:** Development of new **WT** controller functionalities for facilitating *optimization* of wind plant operation over the WPP lifetime
- **Approach:**
 - Develop *new innovative WT control* features ... and use numerical simulations to test and evaluate these
 - Samsung 7MW WT is the test case
 - Power set-point reduction algorithms
 - Active yaw control
 - Model predictive controller
 - Individual pitch control using tower-top sensors
 - Lidar assisted control for load reduction



WP3 - Enhanced WT control schemes (2)

- Full-scale *validation* and *testing* using the Samsung 7MW WT
 - Forward-facing scanning LiDAR on the nacelle (inflow)
 - Rear-facing LiDAR resolving the effect of control actions on the wake



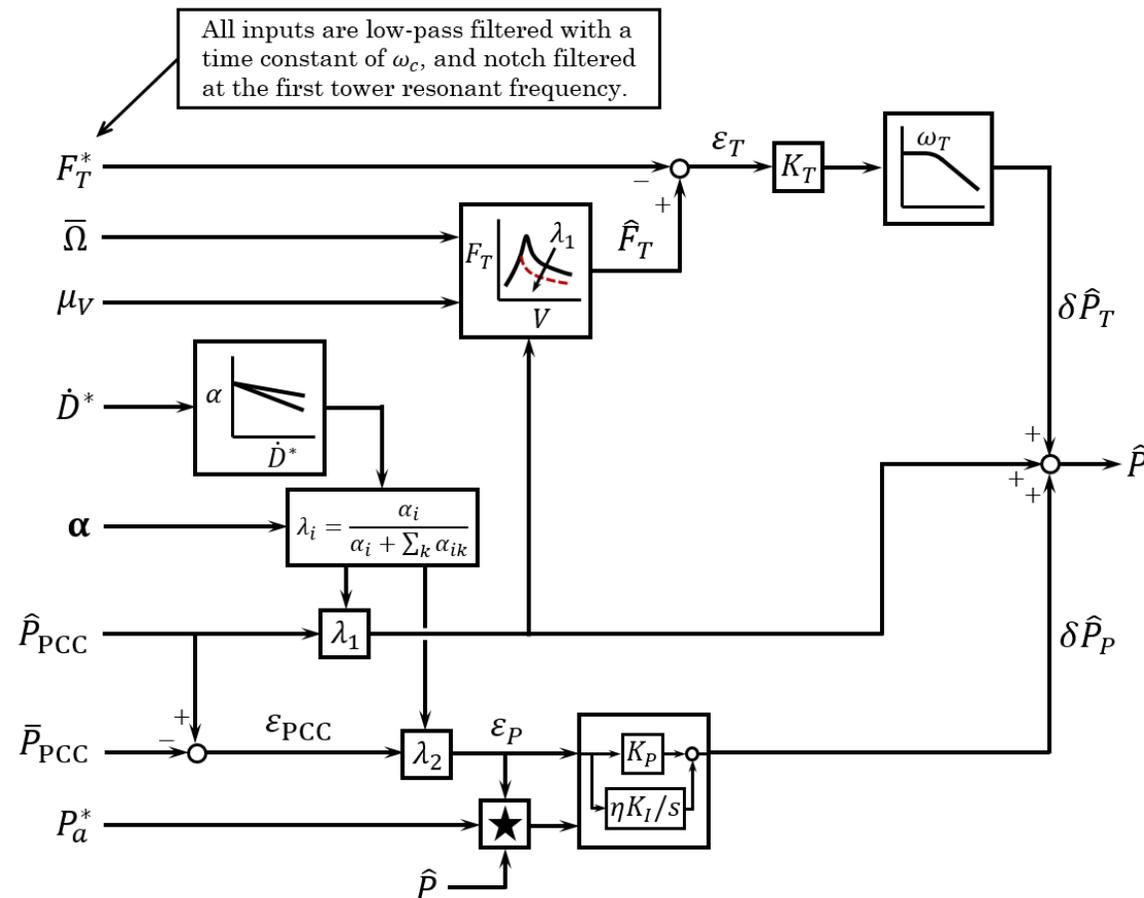
WP₄ - Closed loop control schemes (1)

- **Objectives:** *Unification of the results* from other WPs into a suite of practical wind power plant controllers + develop *guidelines* and *standards* for the design of wind power plants with advanced control functions
- **Approach:**
 - "Closes the loop" on the open-loop wake control strategies developed in WP₂, by
 - Accounting for *model uncertainty*
 - Accounting for *stochastic (short term) variability* of external conditions ... based on on-line input from e.g. electrical sensors, wind speed sensors, and condition monitoring equipment



WP4 - Closed loop control schemes (2)

- Hierarchical wind power plant supervisory controller ... a complex linear approach



WP5 Dissemination

Website: totalcontrolproject.eu



ABOUT US

AMBITION

CONSORTIUM

DISSEMINATION

MODELLING AND VALIDATION



Welcome to the project Totalcontrol lead by DTU Wind Energy.

This project is funded by



TotalControl is an EU Horizon2020 funded project running from 2018-2021.



Thank You!

Questions?



11 December 2020

